

## Exercise 6

### 1 Emulating a $(1, N)$ Register from $(1, 1)$ Registers

Consider the implementation in Algorithm 1 of a  $(1, N)$  register, instance  $onr$ , from an array of  $N$  instances of so-called *base registers*. This algorithm sends no messages explicitly, it merely reduces one abstraction to another one. It is an example of an algorithm in the so-called *shared memory-model*.

The unique writer process of the  $(1, N)$  register is  $p$ . The base registers are  $(1, 1)$  registers, denoted  $br.q$  for  $q \in \Pi$ , such that only process  $p$  may write to instance  $br.q$  and only process  $q$  may read from it. (Recall that *self* denotes the process executing the algorithm. The consistency property of the registers, whether they are safe, regular, or atomic, is specified later.)

---

**Algorithm 1:** Multi-Reader Emulation

---

**Implements:**

$(1, N)$ -Register, **instance**  $onr$ . // the writer is  $p$

**Uses:**

$(1, 1)$ -Register (multiple instances).

**upon event**  $\langle onr, Init \rangle$  **do**

$writeset := \emptyset$ ;

**forall**  $q \in \Pi$  **do**

Initialize a new instance  $br.q$  of  $(1, 1)$ -Register with writer  $p$  and reader  $q$ ;

**upon event**  $\langle onr, Read \rangle$  **do**

**trigger**  $\langle br.self, Read \rangle$ ;

**upon event**  $\langle br.self, ReadReturn \mid v \rangle$  **do**

**trigger**  $\langle onr, ReadReturn \mid v \rangle$ ;

**upon event**  $\langle onr, Write \mid v \rangle$  **do** // only the writer  $p$

**forall**  $q \in \Pi$  **do**

**trigger**  $\langle br.q, Write \mid v \rangle$ ;

**upon event**  $\langle br.q, WriteReturn \rangle$  **do** // only the writer  $p$

$writeset := writeset \cup \{q\}$ ;

**if**  $writeset = \Pi$  **then**

$writeset := \emptyset$ ;

**trigger**  $\langle onr, WriteReturn \rangle$ ;

---

Answer these questions and justify your answers:

- (a) Let the array  $br.q$  for  $q \in \Pi$  be *safe* binary  $(1, 1)$ -registers. Show that the emulation produces a *safe* binary  $(1, N)$ -register instance  $onr$ .
- (b) If we replace the  $N$  safe registers  $br.q$  for  $q \in \Pi$  with an array of *regular binary*  $(1, 1)$ -registers (i.e., registers that only store one bit), does the algorithm implement a *regular binary*  $(1, N)$ -register?
- (c) If we replace the  $N$  safe registers  $br.q$  for  $q \in \Pi$  with an array of *regular multi-valued*  $(1, 1)$ -registers, does the algorithm implement a *regular multi-valued*  $(1, N)$ -register?

## 2 Reliable Storage with Crashes and Recoveries

In the fail-recovery model we consider crash-recovery process failures [CGR11, Section 2.2.4]. This means that also a correct process may crash, as long as it recovers later. To be more precise, a *correct* process in this model is one that either never crashes or one that eventually recovers and never crashes again. All other processes are *faulty*.

When a process recovers, a special  $\langle \textit{Recovery} \rangle$  event is triggered by the runtime system; an algorithm can react accordingly. All local state of a process is lost after a crash, apart from data in *stable storage*. A process has two operations, called *store* and *retrieve*, for writing to and reading from stable storage. The content of stable storage is not affected by crashes.

Modify the “Majority Voting” algorithm for a  $(1, N)$  regular register, which was discussed in class, so that it works in the fail-recovery model. Try to store as few variables in stable storage as needed.

Your algorithm should use *stubborn point-to-point links* and *stubborn best-effort broadcast* primitives [CGR11, Sections 2.4.3 and 3.5.1], which are defined just like point-to-point links and best-effort broadcast primitives, except that they deliver every message sent on them not only once (as usual) but over and over (infinitely many times). This is needed for the fail-recovery model, and implies your algorithm should filter duplicate messages.

## 3 Flooding Uniform Consensus

Can we optimize Algorithm 5.3 [CGR11] (Flooding Uniform Consensus) to save one or more communication rounds? More precisely, can it be modified such that all correct processes always decide after  $N - 1$  or fewer rounds? (Consider a system of two processes only.)